NAG C Library Function Document

nag zpbstf (f08utc)

Purpose 1

nag zpbstf (f08utc) computes a split Cholesky factorization of a complex Hermitian positive-definite band matrix.

2 Specification

void nag_zpbstf (Nag_OrderType order, Nag_UploType uplo, Integer n, Integer kb, Complex bb[], Integer pdbb, NagError *fail)

3 Description

nag zpbstf (f08utc) computes a split Cholesky factorization of a complex Hermitian positive-definite band matrix B. It is designed to be used in conjunction with nag_zhbgst (f08usc).

The factorization has the form $B = S^H S$, where S is a band matrix of the same bandwidth as B and the following structure: S is upper triangular in the first (n+k)/2 rows, and transposed hence, lower triangular in the remaining rows. For example, if n = 9 and k = 2, then

$$S = \begin{pmatrix} s_{11} & s_{12} & s_{13} & & & & \\ & s_{22} & s_{23} & s_{24} & & & & \\ & & s_{33} & s_{34} & s_{35} & & & & \\ & & & s_{44} & s_{45} & & & & \\ & & & & s_{55} & & & & \\ & & & & s_{64} & s_{65} & s_{66} & & & \\ & & & & s_{75} & s_{76} & s_{77} & & \\ & & & & & s_{86} & s_{87} & s_{88} & \\ & & & & & & s_{97} & s_{98} & s_{99} \end{pmatrix}.$$

4 References

None.

5 Parameters

 $order-Nag_OrderType$ 1:

> On entry: the order parameter specifies the two-dimensional storage scheme being used, i.e., rowmajor ordering or column-major ordering. C language defined storage is specified by $order = Nag_RowMajor$. See Section 2.2.1.4 of the Essential Introduction for a more detailed explanation of the use of this parameter.

Constraint: order = Nag_RowMajor or Nag_ColMajor.

2: uplo – Nag UploType

On entry: indicates whether the upper or lower triangular part of B is stored as follows:

if $uplo = Nag_Upper$, the upper triangular part of B is stored;

if $uplo = Nag_Lower$, the lower triangular part of B is stored.

Constraint: **uplo** = **Nag_Upper** or **Nag_Lower**.

Input

Input

3: **n** – Integer

On entry: n, the order of the matrix B.

Constraint: $\mathbf{n} \ge 0$.

4: **kb** – Integer

On entry: k, the number of super-diagonals of the matrix B if $uplo = Nag_Upper$, or the number of sub-diagonals if $uplo = Nag_Lower$.

Constraint: $\mathbf{kb} \ge 0$.

5: $\mathbf{bb}[dim] - \text{Complex}$

Note: the dimension, dim, of the array **bb** must be at least $max(1, pdbb \times n)$.

On entry: the n by n Hermitian band matrix B. This is stored as a notional two-dimensional array with row elements or column elements stored contiguously. The storage of elements b_{ij} depends on the **order** and **uplo** parameters as follows:

if order = Nag_ColMajor and uplo = Nag_Upper, b_{ij} is stored in bb $[k + i - j + (j - 1) \times pdbb]$, for i = 1, ..., n and j = i, ..., min(n, i + k); if order = Nag_ColMajor and uplo = Nag_Lower,

 b_{ij} is stored in $\mathbf{bb}[i-j+(j-1)\times\mathbf{pdbb}]$, for $i=1,\ldots,n$ and $j=\max(1,i-k),\ldots,i$;

if order = Nag_RowMajor and uplo = Nag_Upper, b_{ij} is stored in $bb[j - i + (i - 1) \times pdbb]$, for i = 1, ..., n and j = i, ..., min(n, i + k);

if order = Nag_RowMajor and uplo = Nag_Lower, b_{ij} is stored in $bb[k+j-i+(i-1) \times pdbb]$, for i = 1, ..., n and j = max(1, i-k), ..., i.

On exit: B is overwritten by the elements of its split Cholesky factor S.

6: **pdbb** – Integer

On entry: the stride separating row or column elements (depending on the value of **order**) of the matrix B in the array **bb**.

Constraint: $pdbb \ge kb + 1$.

7: fail – NagError *

The NAG error parameter (see the Essential Introduction).

6 Error Indicators and Warnings

NE_INT

On entry, $\mathbf{n} = \langle value \rangle$. Constraint: $\mathbf{n} \ge 0$.

On entry, $\mathbf{kb} = \langle value \rangle$. Constraint: $\mathbf{kb} \geq 0$.

On entry, $\mathbf{pdbb} = \langle value \rangle$. Constraint: $\mathbf{pdbb} > 0$.

NE_INT_2

On entry, $\mathbf{pdbb} = \langle value \rangle$, $\mathbf{kb} = \langle value \rangle$. Constraint: $\mathbf{pdbb} \geq \mathbf{kb} + 1$. Input

Input

Output

Input

Inr

Input/Output

NE_CONVERGENCE

The factorization could not be completed, because updated element $b(\langle value \rangle, \langle value \rangle)$ would be the square root of a negative number. Hence *B* is not positive definite. This may indicate an error in forming the matrix *B*.

NE_ALLOC_FAIL

Memory allocation failed.

NE_BAD_PARAM

On entry, parameter $\langle value \rangle$ had an illegal value.

NE_INTERNAL_ERROR

An internal error has occurred in this function. Check the function call and any array sizes. If the call is correct then please consult NAG for assistance.

7 Accuracy

The computed factor S is the exact factor of a perturbed matrix B + E, where

$$|E| \le c(k+1)\varepsilon|S^H||S|,$$

c(k+1) is a modest linear function of k+1, and ε is the *machine precision*. It follows that $|e_{ij}| \le c(k+1)\varepsilon\sqrt{(b_{ii}b_{jj})}$.

8 Further Comments

The total number of floating-point operations is approximately $4n(k+1)^2$, assuming $n \gg k$.

A call to this function may be followed by a call to nag_zhbgst (f08usc) to solve the generalized eigenproblem $Az = \lambda Bz$, where A and B are banded and B is positive-definite.

The real analogue of this function is nag_dpbstf (f08ufc).

9 Example

See Section 9 of the document for nag_zhbgst (f08usc).